

Recall:  $\gamma: [a, b] \rightarrow M$  is a geodesic if  $D_{\gamma'} \gamma' = 0$ .

( $\Rightarrow$ ) ①  $|\gamma'| \equiv \text{const.}$

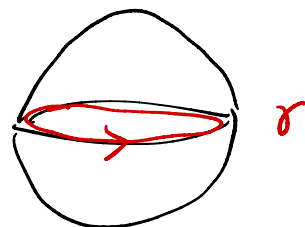
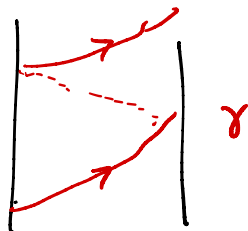
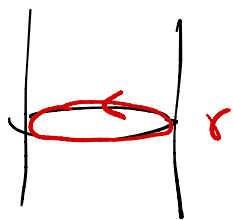
②  $\gamma'' = k_n \cdot N + k_g \cdot n$  where  $k_g \equiv 0$ .

( $\Leftarrow$ ) if  $|\gamma'| \equiv 1$  (w.l.o.g.) and  $k_g \equiv 0$ .

then  $(\gamma'')^T = (k_n \cdot N + k_g \cdot n)^T = k_g \cdot n = 0$ .

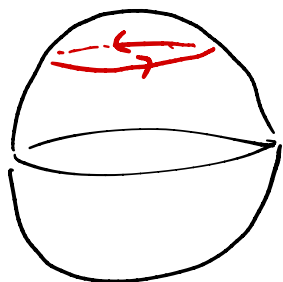
$\Rightarrow D_{\gamma'} \gamma' = 0 \quad \#$

Example: Suppose  $\gamma$  = parametrized by arc-length.



$\Rightarrow \gamma'' \perp T_{\gamma}M \quad \forall t. \quad \Rightarrow k_g \equiv 0 \Rightarrow \text{geodesic.}$

But



$\gamma'' \not\perp T_{\gamma}M.$

$\Rightarrow \gamma \neq \text{geodesic.}$

given  $\alpha: (a, b) \rightarrow M$  a regular curve.

$\alpha = X(u_1(t), u_2(t))$  s.t.  $\alpha' = u_1' X_1 + u_2' X_2$ .

$$\begin{aligned}
\alpha'' &= (u_i' x_i)' \\
&= u_i'' x_i + u_i' (x_{ij} u_j') \\
&= u_i'' x_i + u_i' (\Gamma_{ij}^k x_k u_j' + h_{ij} N u_j') \\
&= (u_k'' + \Gamma_{ij}^k u_i' u_j') x_k + \underbrace{h_{ij} u_i' u_j'}_{= \underline{II}(\alpha', \alpha')} N.
\end{aligned}$$

$$\therefore (D_{\alpha'} \alpha')^T \equiv 0 \iff \boxed{u_k'' + \sum_{i,j} \Gamma_{ij}^k u_i' u_j' \equiv 0 \quad \forall k.} \quad \#$$

Corollary: If  $\varphi: M \rightarrow N$  is isometry and  $\alpha: (a,b) \rightarrow M$  is a geodesic, then  $\beta = \varphi \circ \alpha: (a,b) \rightarrow N$  is also a geodesic.

pf: (Sketch)

Suffice to prove  $\star\star$  for  $\beta$  at each point.

Let  $X: U \rightarrow M$  be a parametrization of  $M$  at  $p = \alpha(t_0)$

then  $\tilde{X}: U \rightarrow N$  given by  $\tilde{X} = \varphi \circ X$  is a parametrization of  $N$ .

$$\begin{cases} \alpha' = u_1' X_1 + u_2' X_2 \\ \beta' = \tilde{u}_1' \tilde{X}_1 + \tilde{u}_2' \tilde{X}_2. \end{cases}$$

(thanks to the choice of parametrization)

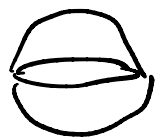
$$\tilde{u}_1' = \underbrace{\downarrow}_{=} u_1', \quad \tilde{u}_2' = \tilde{u}_2'.$$

$$\therefore \tilde{g}_{ij} = g_{ij} \quad \text{by isometry}$$

$$\therefore \tilde{\Gamma}_{ij}^k(\psi(p)) = \Gamma_{ij}^k(p), \quad \forall p \in \mathcal{M}$$

$\Rightarrow \beta$  satisfies geodesic eqn.  $\#$

Example:  $X(u,v) = (f(v) \cos u, f(v) \sin u, g(v))$ ,  $f > 0$ .

eg:   $\left\{ \begin{array}{l} f(v) = \sin v \\ g(v) = \cos v \end{array} \right. \Rightarrow \text{great circle} = \text{geodesic.}$

where great circle:  $\alpha(t) = X(c_0, t)$ .

$$\left\{ \begin{array}{l} X_u = (-f \sin u, f \cos u, 0) \\ X_v = (f_v \cos u, f_v \sin u, g_v) \end{array} \right.$$

if  $\alpha(t) = X(u_0, t)$ , then

$$\alpha'' = (f_{vv} \cos u, f_{vv} \sin u, g_{vv})$$

$$\left\{ \begin{array}{l} \langle \alpha'', X_u \rangle = 0 \\ \langle \alpha'', X_v \rangle = f_{vv} f_v + g_{vv} g_v \\ = \frac{1}{2} (f_v^2 + g_v^2)' \end{array} \right.$$

$\therefore$  if  $f_v^2 + g_v^2 \equiv \text{const} \neq 0$  along  $\alpha(t)$   $\nearrow$  geodesic  $\#$   
 then ①  $|\alpha'| \equiv \text{constant}$  ②  $Rg \equiv 0$

General fact from ODE:

Thm Let  $U$  be open set in  $\mathbb{R}^n$ .

Suppose  $F: U \times (-\varepsilon, \varepsilon) \rightarrow \mathbb{R}^n$  is a smooth map. Then  $\forall p \in U$ ,  $\exists \delta \in (0, \varepsilon)$  s.t. the initial value problem

$$* \begin{cases} X'(t) = F(X(t), t) \\ X(0) = p \end{cases}$$

admits a solution on  $(-\delta, \delta)$ .

Moreover, the sol. is unique.

↓ application.

prop:  $\forall p \in M$ ,  $\forall v \in T_p M$ ,  $\exists \alpha: (-\varepsilon, \varepsilon) \rightarrow M$

which is a geodesic on  $(-\varepsilon, \varepsilon)$  s.t.

$$\alpha(0) = p, \quad \alpha'(0) = v.$$

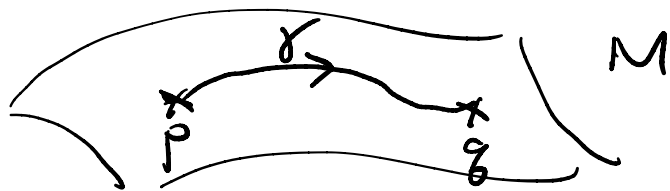
pf (Sketch): geodesic eqn  $\Leftrightarrow u_k'' + \Gamma_{ij}^k u_i' u_j' = 0$

Consider

$$* \begin{cases} \frac{dx_k}{dt} = y_k \\ \frac{dy_k}{dt} = - \sum_{ij} \Gamma_{ij}^k y_i y_j \end{cases}$$

$\Rightarrow$  Sol to  $*$  solves geod. eqn.  $\#$

## Variational perspective:



Let  $\gamma: [a, b] \rightarrow M$  where  $\begin{cases} \gamma(a) = p \\ \gamma(b) = q \end{cases}$ .

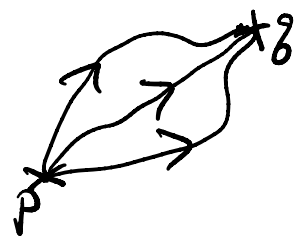
length functional  $L(\gamma) = \int_a^b |\dot{\gamma}| ds$ .

Goal: minimize length functional.

Find local minimizer:  $\gamma(t) = \alpha(t, s)|_{s=0}$

Let  $\alpha: [a, b] \times (-\epsilon, \epsilon) \rightarrow M$  be a one-parameter

family of curve,  $\begin{cases} \alpha(t, 0) = \gamma(t) \\ \alpha(a, s) = p \\ \alpha(b, s) = q \end{cases}$



Defn:  $f(s) = L(\alpha(\cdot, s))$ , then local minimal  $\Rightarrow f'(0) = 0$ .

$$\left. \frac{d}{ds} \right|_{s=0} L(\alpha(s)) = \left. \frac{d}{ds} \right|_{s=0} \int_a^b \langle \dot{\alpha}_t, \dot{\alpha}_t \rangle^{\frac{1}{2}} dt$$

$$= \int_a^b \langle \dot{\alpha}_t, \dot{\alpha}_t \rangle^{-\frac{1}{2}} \langle \dot{\alpha}_{t+s}, \dot{\alpha}_t \rangle dt \Big|_{s=0}$$


$$= \int_a^b \left\langle \frac{\partial}{\partial t} (ds), \frac{d}{dt} \right\rangle dt \Big|_{s=0}$$

$$= - \int_a^b \left\langle ds, \frac{\partial}{\partial t} \left( \frac{d}{dt} \right) \right\rangle dt \Big|_{s=0} \quad \left[ \begin{array}{l} \because ds(a) = \\ ds(b) = 0 \end{array} \right]$$

,  $\forall W = ds$  where  $W(a) = W(b) = 0$ .

(ie.  $\forall$  variation fixing the end points.)

By taking  $W = \phi \cdot \left( \frac{d}{dt} (|\dot{\gamma}|^{-1} \frac{d\gamma}{dt}) \right)^T$  where

$\phi = \overset{\geq 0}{\text{smooth}}$  for vanishing nearby boundary. 

$$\Rightarrow \left[ \begin{array}{l} \because f'(0) = 0 \\ \forall W \end{array} \right], \text{ iff } \left( \frac{d}{dt} (|\dot{\gamma}|^{-1} \frac{d\gamma}{dt}) \right)^T = 0.$$

$\therefore$  If  $\gamma: [a, b] \rightarrow M$  is parametrized by arc-length <sup>(or proportional to)</sup> and is critical point of length functional, then  $\gamma = \text{geodesic}$ .

Alternatively, define energy of  $\gamma$  by

$$E(\gamma) = \int_a^b \underbrace{|\dot{\gamma}|^2}_{\text{energy density (in } L^2)} dt$$

then for variation  $\alpha : [a, b] \times (-\varepsilon, \varepsilon) \rightarrow M$  of  
 $\gamma : [a, b] \rightarrow M$ .

$$\begin{aligned} \left. \frac{d}{ds} \right|_{s=0} E(\alpha) &= \left. \frac{d}{ds} \right|_{s=0} \int_a^b \langle \alpha', \alpha' \rangle dt \\ &= \int_a^b \langle \partial_t \partial_s \alpha, \partial_t \alpha \rangle dt \Big|_{s=0} \end{aligned}$$

$$\left( \begin{array}{l} \alpha(a, s) = p \\ \alpha(b, s) = q \end{array} \right) = - \int_a^b \langle \partial_s \alpha, \partial_t^2 \alpha \rangle dt \Big|_{s=0}$$

$\Rightarrow$  critical value iff  $(\gamma'')^T = 0$ .

Thm: Suppose  $\gamma =$  regular parametrized curve  
 on  $[a, b]$ .  $\gamma =$  critical value of  $E$  iff  
 $\gamma =$  geodesic.

\* wrt length, changing speed  $\nRightarrow$  change in length  
 wrt energy, tangential acceleration  $\Rightarrow$  Energy change.

$$* \text{ length}(\gamma)^2 \leq (b-a) \cdot \text{Energy}(\gamma).$$

Equality holds iff arc-length parametrization

$\therefore$  minimization in length / Energy  
 are geometrically equivalent.